



# IES

Integrated Energy Systems

# Supervisory Control with Feasible Actuator Range Modifier (FARM)

FORCE Overview and Training

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# 1. FARM capability overview



- FARM: Feasible Actuator Range Modifier
  - FARM is a RAVEN plugin to meet the supervisory control needs.
  - FARM helps validate the issued actuator value, to meet both
    - Explicit constraints, and
    - Implicit constraints.

## • Q1: What are these constraints?

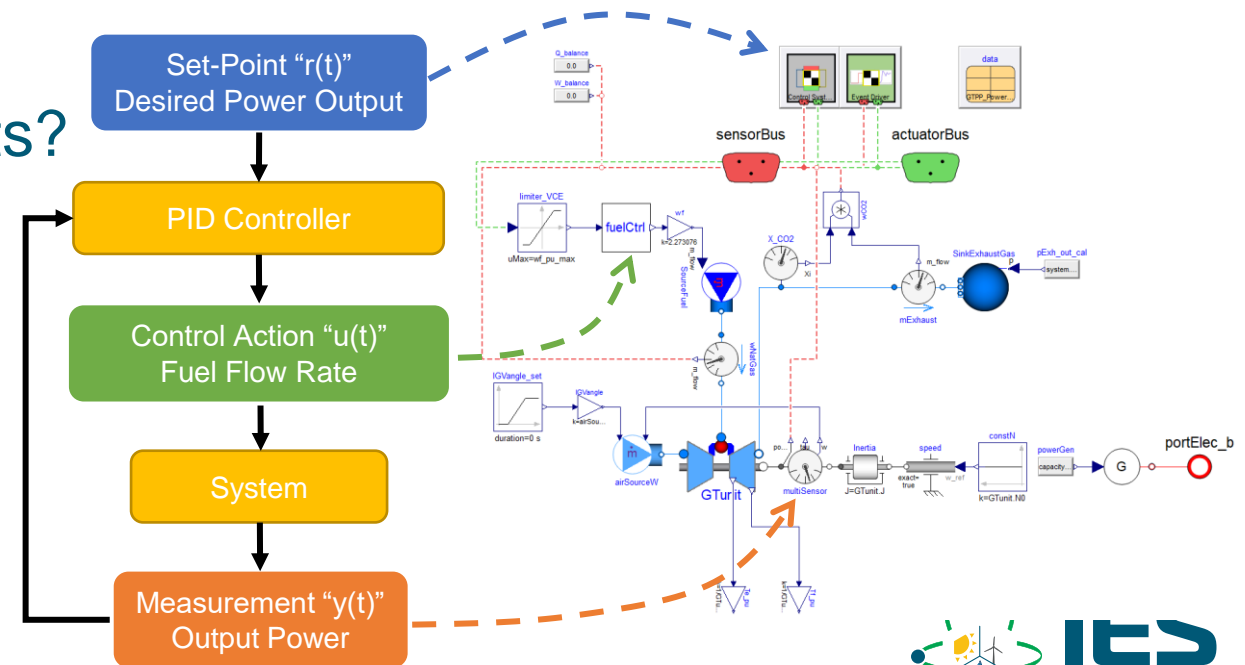
Let's use a Gas Turbine to explain:

Explicit constraints:

- Power output to grid;
- Power ramp rate, etc.

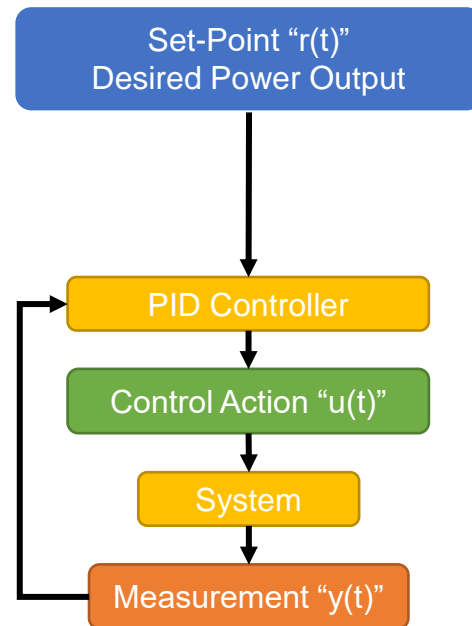
Implicit constraints:

- Firing Temperature, etc.

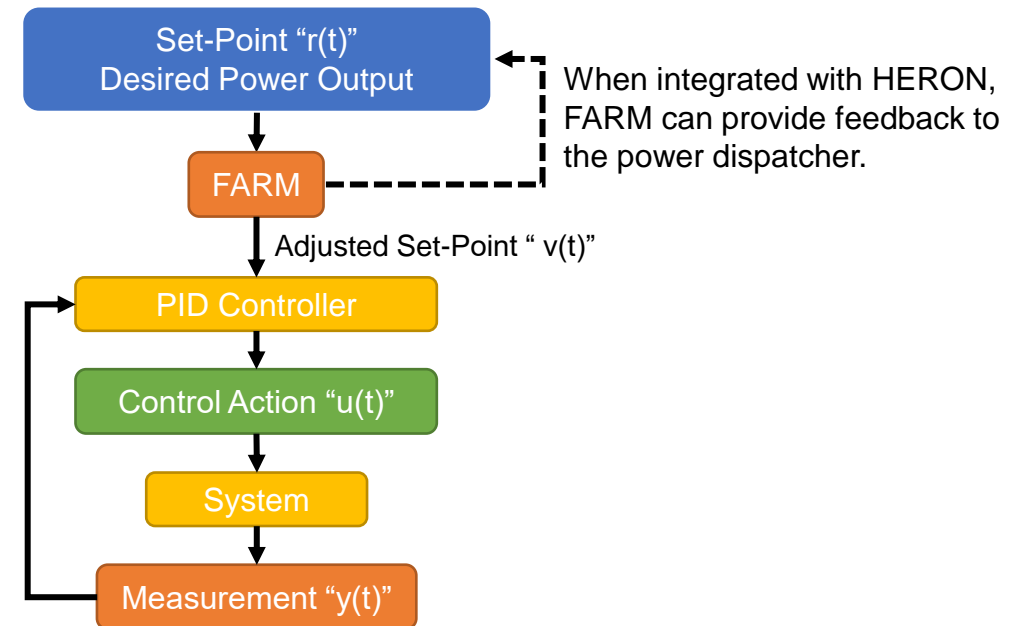


# 1. FARM capability overview

- FARM: Feasible Actuator Range Modifier
  - Q2: Where is FARM in the feedback loop control?



Without FARM

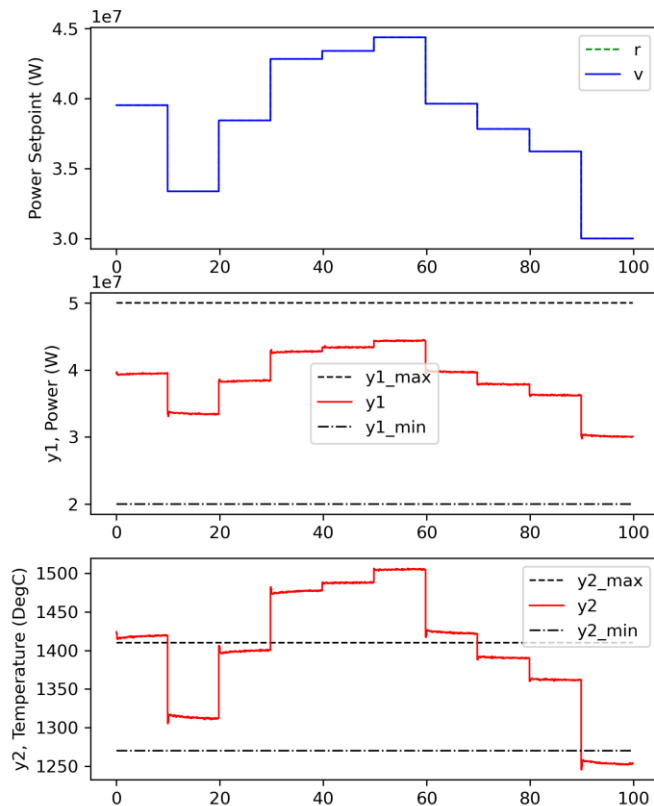


With FARM

# 1. FARM capability overview



- FARM: Feasible Actuator Range Modifier
  - Q3: What's the effects of FARM?

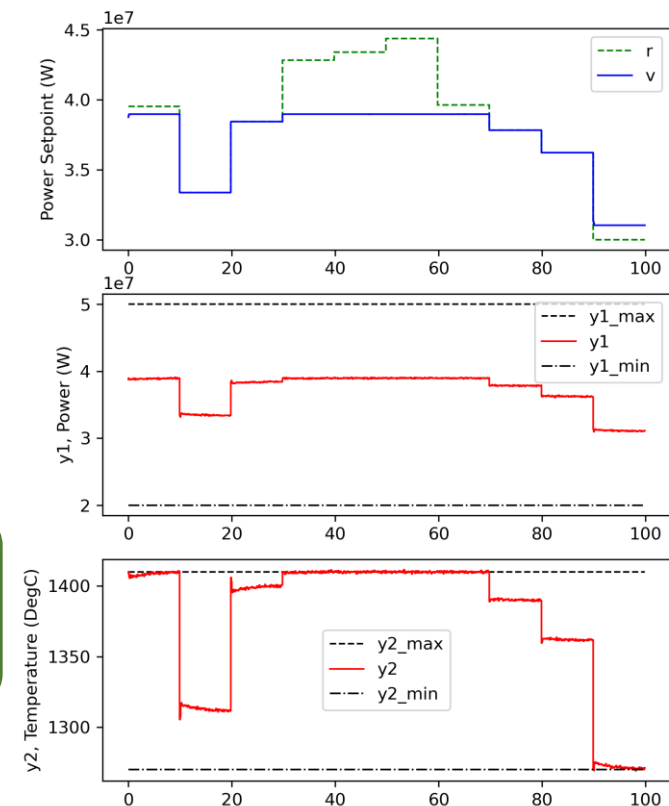


Without FARM:

- System run on original power setpoint
- Implicit constraints were violated (Firing temperature)

With FARM:

- Power setpoint was adjusted
- Implicit constraints were met (Firing temperature)



## 2. Software installation



- FARM is an open-source software
  - <https://github.com/Argonne-National-Laboratory/FARM>
  - In order to run FARM, RAVEN and HERON are pre-requisites.
- FARM installation can be done in 2 ways:

- Install the submodule version of FARM within RAVEN

```
haoyuwang@p075722 MINGW64 /d/GitProjects/official_forks/raven (devel)  
$ ./scripts/install_plugins.py -s FARM
```

- Or: Download FARM source code using git

```
haoyuwang@p075722 MINGW64 /d/GitProjects/training  
$ git clone https://github.com/Argonne-National-Laboratory/FARM.git
```

Then register FARM plugin in RAVEN

```
haoyuwang@p075722 MINGW64 /d/GitProjects/training/raven (devel)  
$ ./scripts/install_plugins.py -s /d/GitProjects/training/FARM/
```



# 3. Regular Usage: FARM as set-point regulator

## 3.a. Input creation and running the code



- FARM uses XML file as input

- One example is in

*FARM / Training / 2023Apr06 /  
input\_2\_FARM\_RG\_para\_SES.xml*

- We will focus on some key entries.

a1. An XML file containing the state-space representation matrices;

a2. FARM external model name;

a3. Input and output variables for FARM;

a4. Prediction time horizon, operational constraints, and system state;

a5. Random number generator for input variables creation

```
1 <Simulation verbosity="silent">
2 <TestInfo ...
12 </TestInfo>
14 <RunInfo>
15 <WorkingDir>DMDc_FARM_Folder</WorkingDir>
16 <Sequence>RGrun, printToFile</Sequence>
17 </RunInfo>
19 <Files>
20 <Input name="ABCMatrices" type="">DMDcCxCoeff.xml</Input>
21 </Files>
23 <Models>
24 <ExternalModel name="RG1" subType="FARM.RefGov_parameterized_SIMO">
25 <!-- 3 output variables -->
26 <outputVariables>V, V_min, V_max </outputVariables>
27 <!-- 4 variables: Issued Setpoint(PwrSet), Adjusted Setpoint(V), bounds of V(Vmin & Vmax) -->
28 <variables> PwrSet, V, V_min, V_max </variables>
29 <!-- steps in MOAS calculation, "g" value -->
30 <constant varName="MOASsteps"> 360 </constant>
31 <!-- lower and upper bounds for y vector, will be internally checked -->
32 <constant varName="Min_Target1"> 20.0E6 </constant>
33 <constant varName="Max_Target1"> 50.0E6 </constant>
34 <constant varName="Min_Target2"> 1270. </constant>
35 <constant varName="Max_Target2"> 1410. </constant>
36 <!-- System state vector "x", optional, with elements separated by comma(,) -->
37 <!-- <constant varName="Sys_State_x"> 30.0E7 </constant> -->
38 </ExternalModel>
39 </Models>
41 <Distributions>
42 <Uniform name="one">
43 <lowerBound>10</lowerBound>
44 <upperBound>55</upperBound>
45 </Uniform>
46 <!-- distribution for PwrSet sampling -->
47 </Distributions>
49 <Samplers>
50 <MonteCarlo name="RG_Sampler">
51 <samplerInit>
52 <limit>20</limit>
53 </samplerInit>
54 <variable name="PwrSet">
55 <distribution>one</distribution>
56 </variable>
57 </MonteCarlo>
```

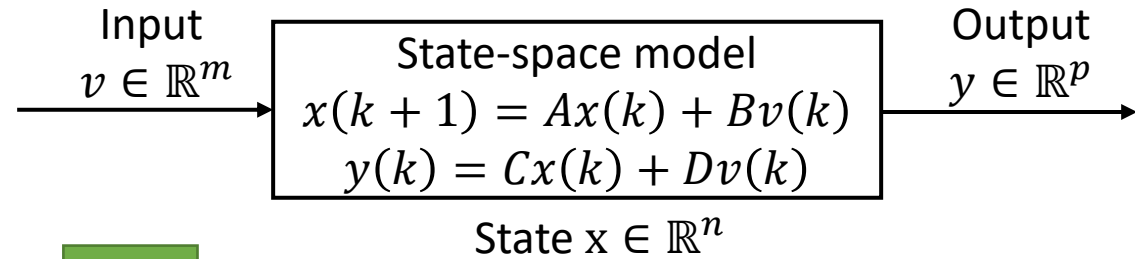
# 3. Regular Usage: FARM as set-point regulator

## 3.a. Input creation and running the code



- a1. An XML file containing the state-space representation matrices
  - A state-space matrix set  $[A, B, C, D]$  is required to describe the system.

One example is available at  
*FARM / Training / 2023Apr06 /  
 DMDc\_FARM\_Folder / DMDcCxCoeff.xml*



- Can be generated through RAVEN DMDc\*.
- Example is available at

*FARM / Training /  
 2023Apr06 /  
 input\_1\_DMDc\_para\_SES.xml*

Time	SES_Demand_MW	Electric_Power	Firing_Temperature	SES.CS.feedback_W_gen.u2	SES.ED.sensorBus.W_gen
1	1.80E+03	1.70E+01	1.70E+07	1.05E+03	1.70E+07
2	1.81E+03	1.70E+01	1.70E+07	1.05E+03	1.70E+07
3	1.82E+03	1.70E+01	1.70E+07	1.05E+03	1.70E+07
4	1.83E+03	1.70E+01	1.70E+07	1.05E+03	1.70E+07
5	1.84E+03	1.70E+01	1.70E+07	1.05E+03	1.70E+07
6	1.85E+03	1.70E+01	1.70E+07	1.05E+03	1.70E+07
7	1.86E+03	1.70E+01	1.70E+07	1.05E+03	1.70E+07
8	1.87E+03	1.70E+01	1.70E+07	1.05E+03	1.70E+07
9	1.88E+03	1.70E+01	1.70E+07	1.05E+03	1.70E+07
10	1.89E+03	1.70E+01	1.70E+07	1.05E+03	1.70E+07
11	1.90E+03	1.70E+01	1.70E+07	1.05E+03	1.70E+07
12	1.91E+03	1.70E+01	1.70E+07	1.05E+03	1.70E+07
13	1.92E+03	1.70E+01	1.70E+07	1.05E+03	1.70E+07
14	1.93E+03	1.70E+01	1.70E+07	1.05E+03	1.70E+07
15	1.94E+03	1.70E+01	1.70E+07	1.05E+03	1.70E+07
16	1.95E+03	1.70E+01	1.70E+07	1.05E+03	1.70E+07
17	1.96E+03	1.70E+01	1.70E+07	1.05E+03	1.70E+07
18	1.97E+03	1.70E+01	1.70E+07	1.05E+03	1.70E+07
19	1.98E+03	1.70E+01	1.70E+07	1.05E+03	1.70E+07
20	1.99E+03	1.70E+01	1.70E+07	1.05E+03	1.70E+07
21	2.00E+03	1.70E+01	1.70E+07	1.05E+03	1.70E+07
22	2.01E+03	1.70E+01	1.70E+07	1.05E+03	1.70E+07
23	2.02E+03	1.70E+01	1.70E+07	1.05E+03	1.70E+07
24	2.03E+03	1.70E+01	1.70E+07	1.05E+03	1.70E+07
25	2.03E+03	1.70E+01	1.70E+07	1.05E+03	1.70E+07

RAVEN  
DMDc

```

1 <?xml version="1.0" encoding="UTF-8"?>
2 <DMDcModel name="DMDcCxCoeff.xml" >
3   <DMDcData type="Static">
4     <type>DMDc</type>
5     <features>SES_Demand_MW_schedulingParameter_0_SES_CS_feedback_W_gen.u2_init_SES_ED_sensorBus.W_gen.u2</features>
6     <targets>Time_SES_CS_feedback_W_gen.u2_SES_ED_sensorBus.W_gen.u2</targets>
7     <description> This XML file contains the main information of the DMDc ROM. The method is explained in the user manual.
8   </DMDcData>
9   <DMDcModel>
10    <dmdtype>Home</dmdtype>
11    <rank>2</rank>
12    <actuators>SES_Demand_MW</actuators>
13    <stateVariables>SES_CS_feedback_W_gen.u2_SES_ED_sensorBus.W_gen.u2</stateVariables>
14    <initStateVariables>SES_CS_feedback_W_gen.u2_init_SES_ED_sensorBus.W_gen.u2_init</initStateVariables>
15    <outputs>Electric_Power_Firing_Temperature</outputs>
16    <dmdTimeScale>1800 1810 1820 1830 1840 1850 1860 1870 1880 1890 1900 1910 1920 1930 1940 1950</dmdTimeScale>
17  </DMDcModel>
18  <DMDcSensors>
19    <XName>--</XName>
20    <XName>--</XName>
21    <XName>--</XName>
22    <XName>--</XName>
23  </DMDcSensors>
24  <DMDcOutputs>
25    <XName>--</XName>
26    <XName>--</XName>
27  </DMDcOutputs>
28  <DMDcRealizations>
29    <realization schedulingParameter_0="2.400000e+03" sample="0">
30      <imaginary>0.000000e+00 0.000000e+00 0.000000e+00 0.000000e+00</imaginary>
31      <matrixShape>2,2</matrixShape>
32      <real>1.68644899e-11 -1.68644899e-11 1.68642806e-11 1.68642806e-11</real>
33    </realization>
34    <realization schedulingParameter_0="3.100000e+03" sample="1">
35      <imaginary>0.000000e+00 0.000000e+00 0.000000e+00 0.000000e+00</imaginary>
36      <matrixShape>2,2</matrixShape>
37      <real>1.68644899e-11 -1.68644899e-11 1.68642806e-11 1.68642806e-11</real>
38    </realization>
39    <realization schedulingParameter_0="3.800000e+03" sample="2">
40      <imaginary>0.000000e+00 0.000000e+00 0.000000e+00 0.000000e+00</imaginary>
41      <matrixShape>2,2</matrixShape>
42      <real>1.68644899e-11 -1.68644899e-11 1.68642806e-11 1.68642806e-11</real>
43    </realization>
44    <realization schedulingParameter_0="4.500000e+03" sample="3">
45      <imaginary>0.000000e+00 0.000000e+00 0.000000e+00 0.000000e+00</imaginary>
46      <matrixShape>2,2</matrixShape>
47      <real>1.68644899e-11 -1.68644899e-11 1.68642806e-11 1.68642806e-11</real>
48    </realization>
49    <realization schedulingParameter_0="5.200000e+03" sample="4">
50      <imaginary>0.000000e+00 0.000000e+00 0.000000e+00 0.000000e+00</imaginary>
51      <matrixShape>2,2</matrixShape>
52      <real>1.68644899e-11 -1.68644899e-11 1.68642806e-11 1.68642806e-11</real>
53    </realization>
54  </DMDcRealizations>
55 </DMDcModel>
56 </DMDcModel>

```



# 3. Regular Usage: FARM as set-point regulator

## 3.a. Input creation and running the code



- a2. FARM external model name;
  - To use FARM, “FARM.RefGov\_parameterized\_SIMO” need to be specified as the external model.
  - Source code\* is available at  
*FARM / src / RefGov\_parameterized\_SIMO.py*
- a3. Input and output variables for FARM;
  - Input: “PwrSet”, the power setpoint before any adjustment;
    - “PwrSet” should share the same unit as the actuator signal in DMDc training data;
  - Output: “V”, adjusted power setpoint; “V\_min” and “V\_max”, the min & max allowed V value.
- a4. “MOASsteps” for the prediction time horizon;
  - $MOASsteps = \frac{\text{Time Horizon}}{\text{Matrices interval}}$
  - Example:
    - To predict the response for 1 hour;
    - Matrices are in 10s interval
    - $MOASsteps = 3600s / 10s = 360$ .

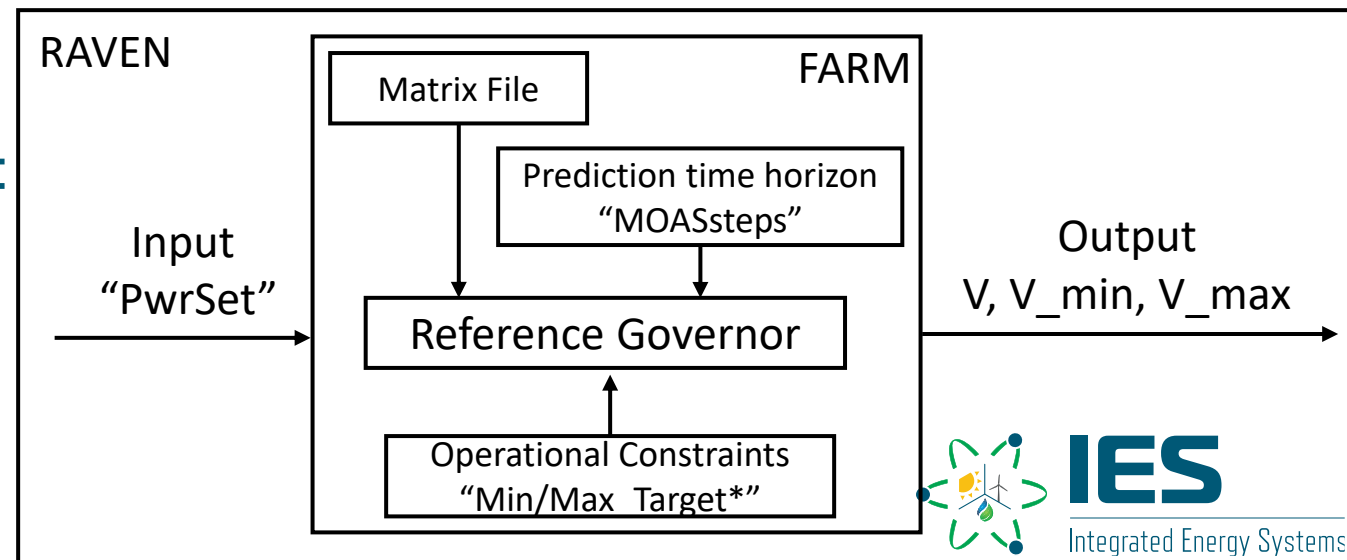
# 3. Regular Usage: FARM as set-point regulator

## 3.a. Input creation and running the code



- a4. “Min/Max\_Target\*” for the operational constraints;
  - “Min\_Target<sub>i</sub>” and “Max\_Target<sub>i</sub>” defines the bounds for the i<sup>th</sup> system output  $y_i$ .
  - Example:
    - In training data,  $y_1$  is Electric Power (W),  $y_2$  is Firing Temperature (°C)
    - Then in the FARM input file,
      - Min\_Target<sub>1</sub>=20.0E6, Max\_Target<sub>1</sub>=50.0E6 → 20.0MW < Electric Power < 50.0MW
      - Min\_Target<sub>2</sub>=1270.0, Max\_Target<sub>2</sub>=1410.0 → 1270°C < Firing Temperature < 1410°C
    - Mind the units.

- The structure of entire FARM Plugin:



# 3. Regular Usage: FARM as set-point regulator

## 3.a. Input creation and running the code



- The FARM input file can be executed like other RAVEN input files:

```
haoyuwang@p075722 MINGW64 /d/GitProjects/wanghy_fork/FARM (dev1)
```

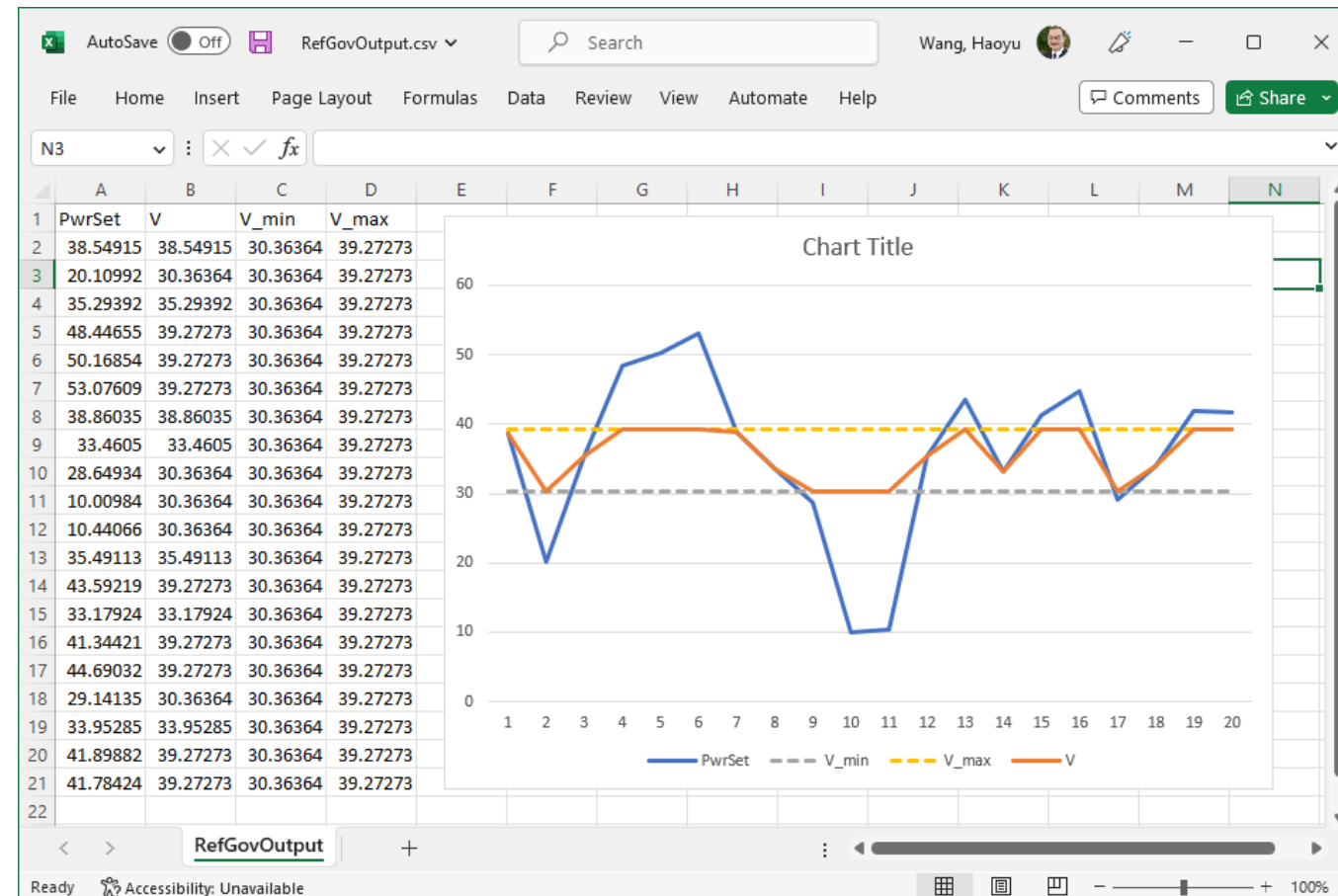
```
$ ../raven/raven_framework Training/2023Apr06/input_2_FARM_RG_para_SES.xml
```

# 3. Regular Usage: FARM as set-point regulator

## 3.b. Output analysis



- The FARM output can be found in:
  - FARM / Training / 2023Apr06 / DMDc\_FARM\_Folder / RefGovOutput.csv
- 20 entries, with 4 column in each entry
  - Issued power setpoint “PwrSet”;
  - Adjusted power setpoint “V”;
  - Minimum allowed value “V\_min”;
  - Maximum allowed value “V\_max”;
- The “PwrSet” are regulated to “V”, to meet both explicit and implicit constraints.

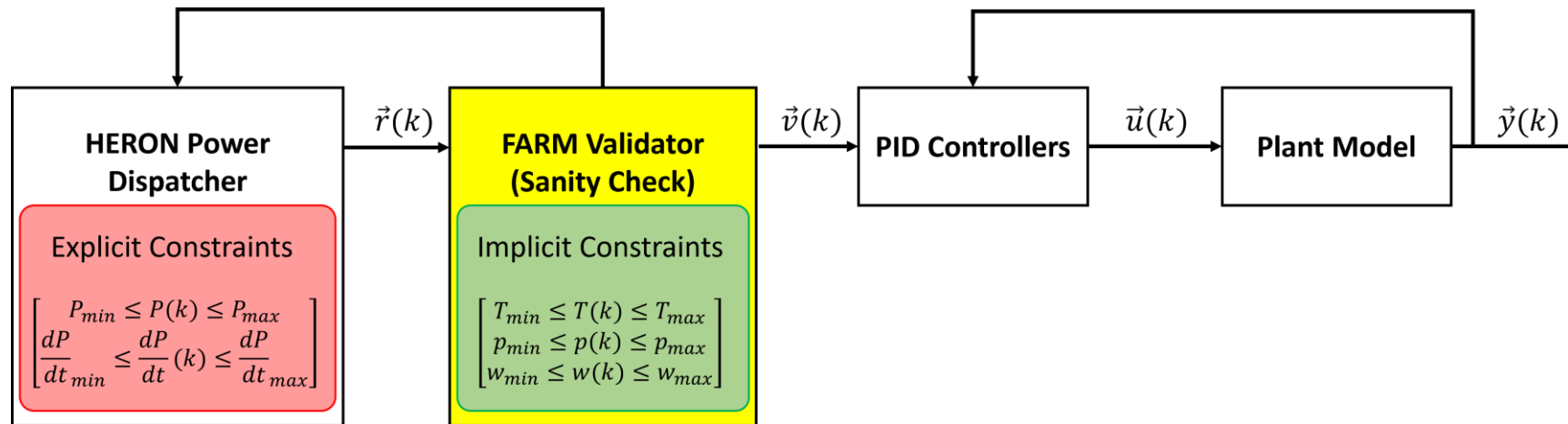


# 4. Advanced Usage: FARM as HERON validator



## 4.a. Overview

- FARM validates the power set-points issued by HERON:
  - Ensure the implicit constraints are met within the dispatch interval;
  - If not, provide feedback to HERON for re-optimization

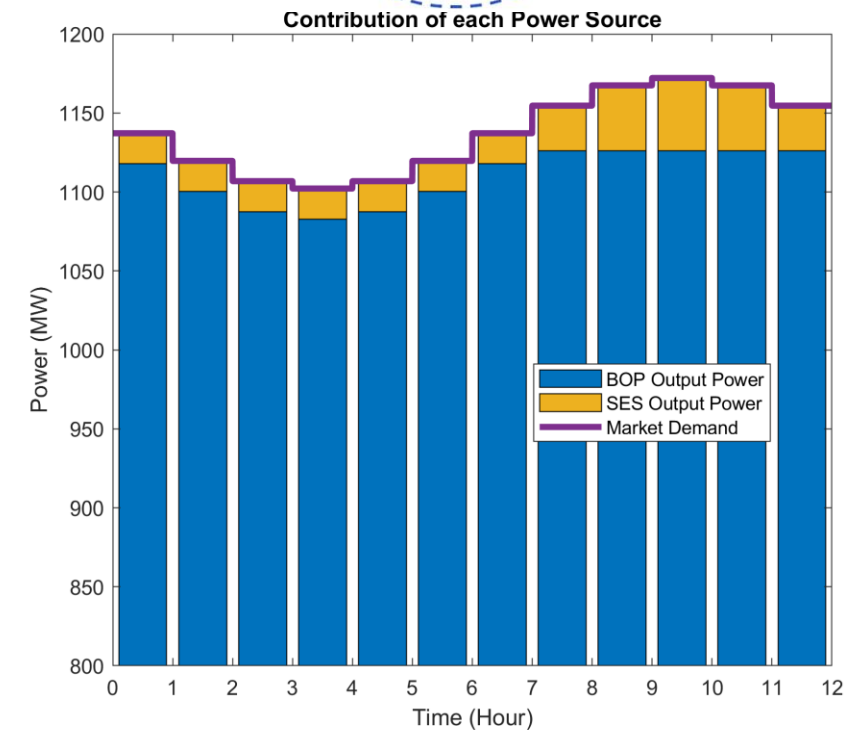
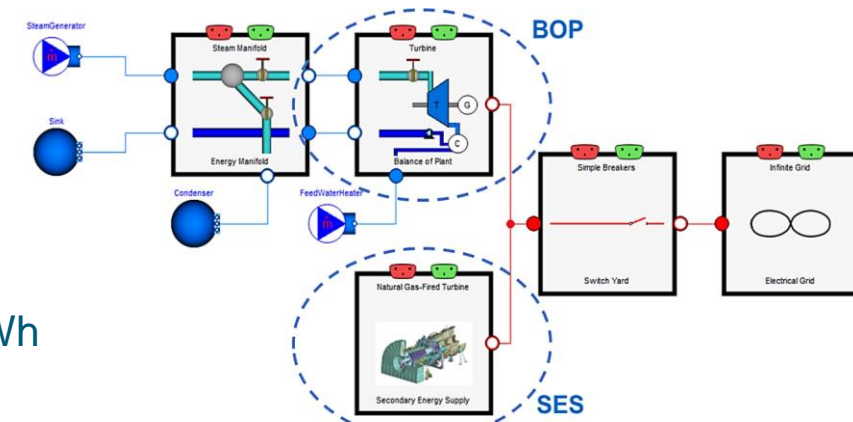


# 4. Advanced Usage: FARM as HERON validator

## 4.b. Example



- Two-plant IES unit:
  - Balance of Plant:
    - Steam Turbine, 1350MWe, Cost of Generation \$100 USD / MWh
  - Secondary Energy Source:
    - Natural Gas Turbine, 50MWe, Cost of Generation \$200 USD / MWh
- Market Demand:
  - 12 hour-long sinusoidal trajectory
  - 1137±35 MW
  - Sale price: \$400 USD / MWh
- Economically preferred solution:
  - Run BOP at maximum allowed power (due to low cost)
  - Use SES during peak demand



Question: Why is SES at non-zero power at low demand?

# 4. Advanced Usage: FARM as HERON validator

## 4.b. Example



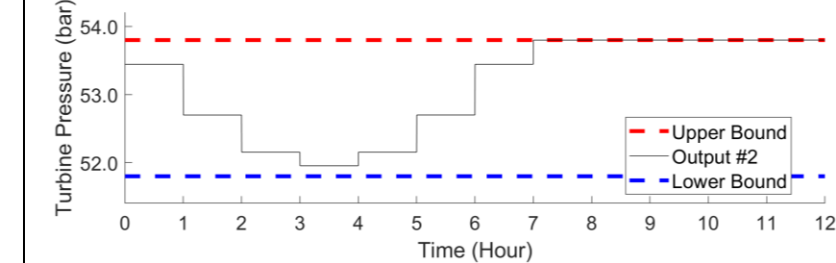
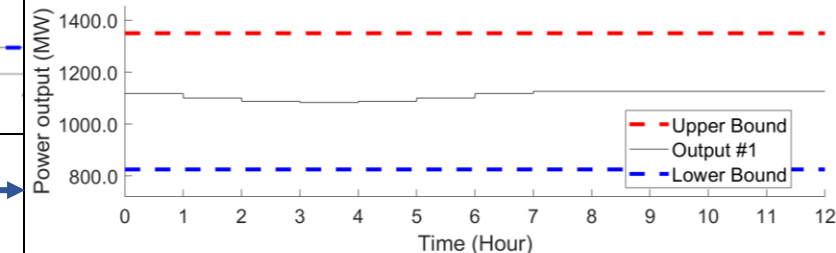
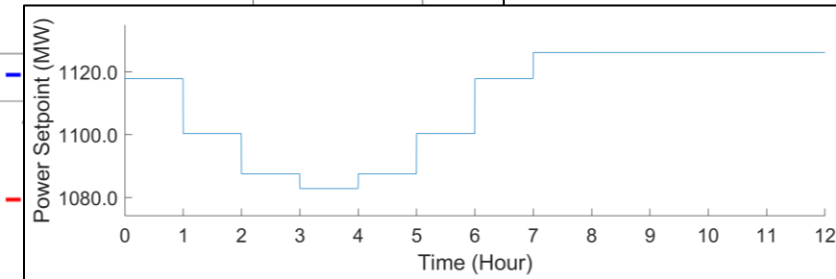
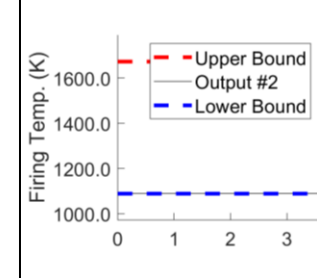
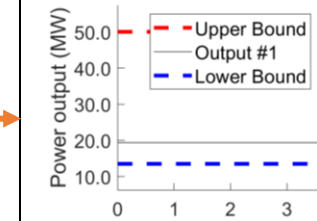
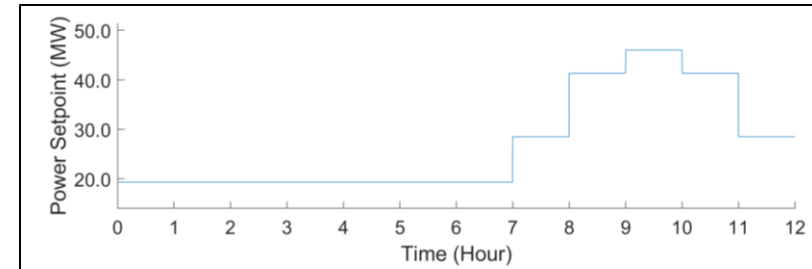
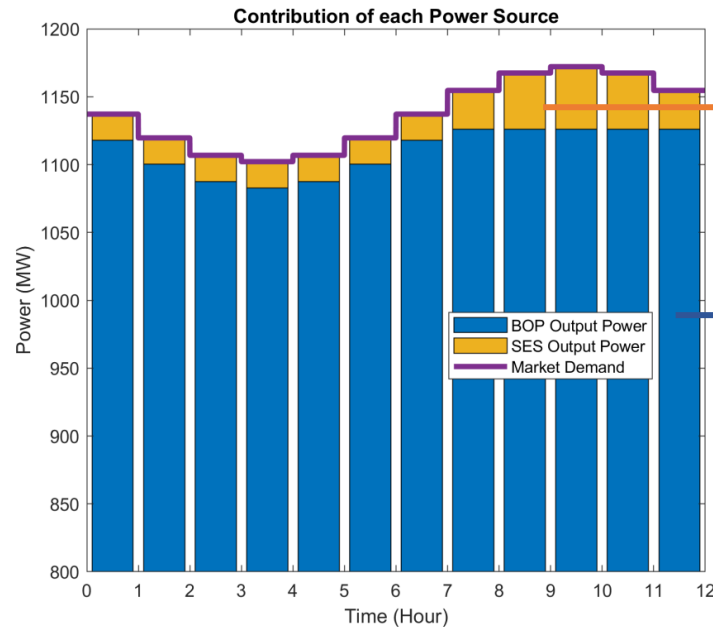
- Constraint Enforcement

- SES:

- Electrical Power: 13.5 MW – 50.0 MW
- Firing Temperature: 1089.0 K – 1673.0 K

- BOP:

- Electrical Power: 825 MW – 1350 MW
- Turbine Pressure: 51.8 bar – 53.8 bar

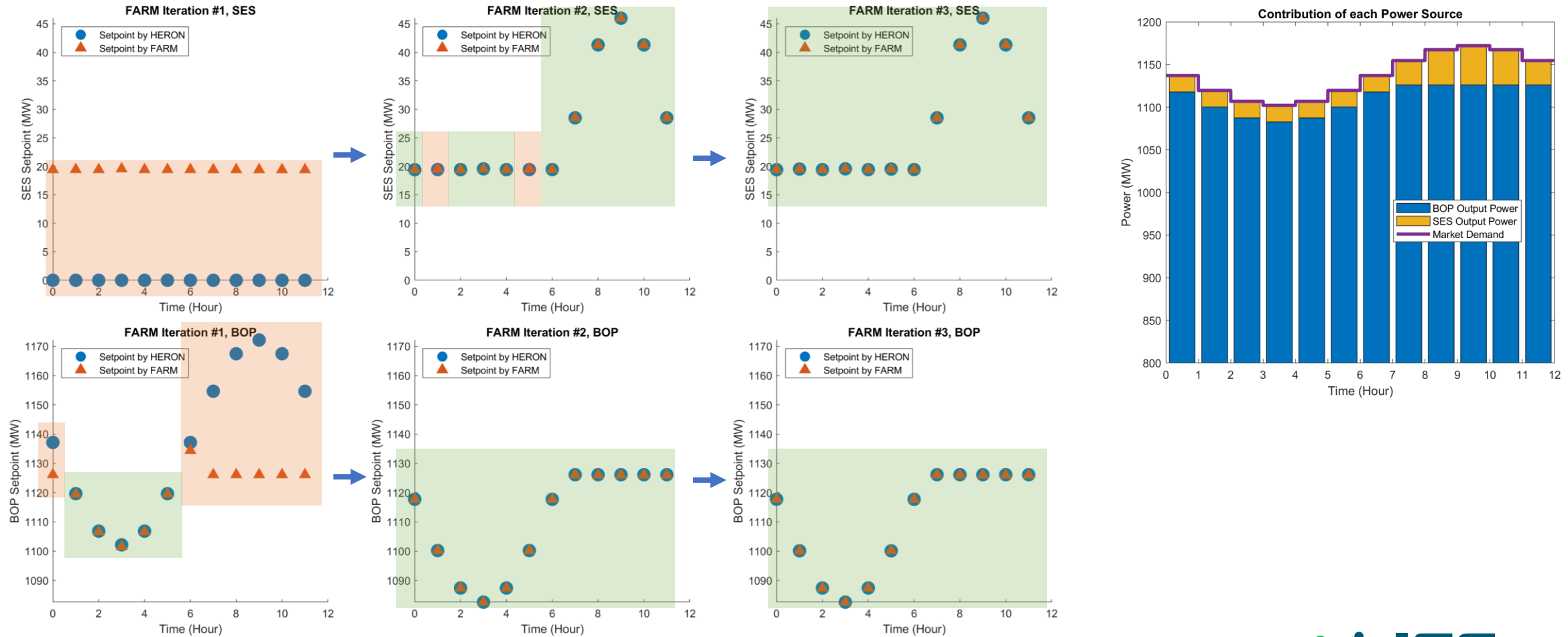


# 4. Advanced Usage: FARM as HERON validator

## 4.b. Example



- Optimal solution is achieved after multiple feedback iterations



Example is available at: [FARM / tests / heron\\_validator / FARM\\_Gamma\\_FMU / heron\\_input\\_FARM\\_gammaFMU\\_BOP\\_SES.xml](https://ies.inl.gov/FARM/tests/heron_validator/FARM_Gamma_FMU/heron_input_FARM_gammaFMU_BOP_SES.xml)



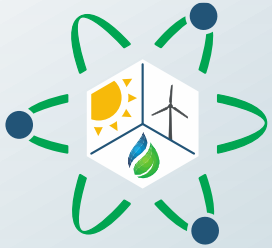
# 5. Future Directions



- Multi-Input-Multi-Output version of FARM will be implemented as set-point regulator (ETA: June 2023)
  - The prototype is developed as HERON validator (“FARM-Delta”[1]);
  - Some redundancy reduction algorithms need to be optimized.
- FARM will aid operations in experimental facilities (ETA: 2024)

## References

[1] Haoyu Wang, Roberto Poncioli, Akshay J. Dave, and Richard B. Vilim. Control system for multi-system coordination via a single reference governor. No. ANL/NSE-22/26. Argonne National Lab.(ANL), Argonne, IL (United States), 2022.



# IES

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# Thank you!

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